



Almega Friendly series II **Arc Welding Robot** ***FD-V8***



**Faster, Slimmer,
& more User-Friendly**

**Improved in every aspect of
performance!**



**The maximum payload is increased to 8kg.
Application for the welding usage has been
expanded.**

Improved in every aspect of performance!

Faster cycle time

Due to the industry's fastest speeds, cycle times are reduced.

Slim design

Slimmed lower arm and reduced rotating radius. Avoiding the interference with jigs or workpieces.

User-friendly operation

All cables required for Synchro-feed welding are also built in the lower arm. Avoiding the interference behind the arm.

Stronger structure

The maximum payload has been increased by 30%, up to 8kg. Enabling the use of a variety of torches and sensors. It is also good for handling application.

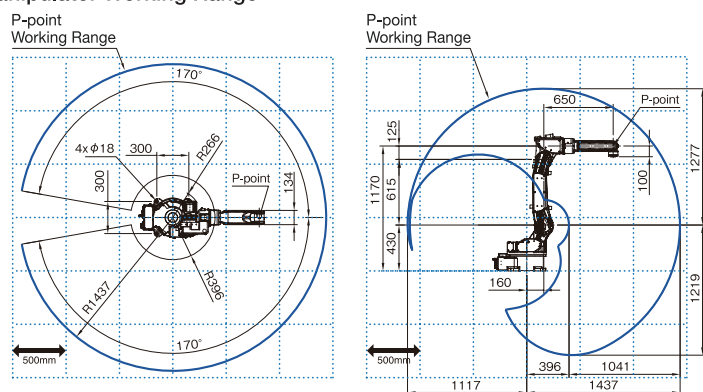
Manipulator Specifications

	FD-V8
Structure	Vertical articulated type
Number of Axes	6
Max. Payload Capacity	8kg
Positional Repeatability	±0.08mm (Note 1)
Drive System	AC servomotor
Drive Capacity	3016W
Position Feedback	Absolute encoder
Working Range	J1 (Rotation) ±170° (±50°) (Note 2)
	Arm J2 (Lower arm) -155°~+90°
	J3 (Upper arm) -170°~+190°
	J4 (Swing) ±180°
	Wrist J5 (Bending) -50°~+230°
	J6 (Twist) ±360° (Note 3)
Maximum Speed	J1 (Rotation) 4.19rad/s (240°/s) (3.32rad/s (190°/s)) (Note 2)
	Arm J2 (Lower arm) 4.19rad/s (240°/s)
	J3 (Upper arm) 4.01rad/s (230°/s)
	J4 (Swing) 7.50rad/s (430°/s)
	Wrist J5 (Bending) 7.50rad/s (430°/s)
	J6 (Twist) 11.00rad/s (630°/s)
Allowable Load	J4 (Swing) 17.6N·m
	J5 (Bending) 17.6N·m
	J6 (Twist) 7.8N·m
	Wrist Allowable Moment of Inertia J4 (Swing) 0.43kg·m ²
	J5 (Bending) 0.43kg·m ²
	J6 (Twist) 0.09kg·m ²
Arm Cross-sectional Area	3.11m ² ×340°
Ambient Conditions	Temp: 0 to 45°C, Hmd: 20 to 80%RH (No Condensation)
Mass (weight)	140kg
Upper Arm Payload Capacity	10kg (Note 4)
Installation Type	Floor, wall, or ceiling
Paint Color	White (Munsell notation 10GY 9/1)

Notes

1. Positional repeatability of the tool center point (TCP) value complies with the JIS-B-8432 Standard.
2. Specifications for wall mounting appear in parentheses.
3. The working range of the J2 axis may be restricted when wall-mounted.
4. The capacity of the upper arm varies with the wrist capacity.

Manipulator Working Range



In accordance with DAIHEN's policy to make continuing improvements, design and/or specifications are subject to change without notice and without any obligation on the part of manufacturer.

DAIHEN Corporation

4-1, Koyochō-nishi, Higashinada-ku, Kobe, Hyogo 658-0033, Japan
 Phone: (Country Code 81) 78-275-2006
 Fax: (Country Code 81) 78-845-8159

Distributed by:



潤 達 企 業 有 限 公 司
 上海潤漢機械設備貿易有限公司

(日本 DAIHEN Corporation 代理商)

潤達企業有限公司：桃園市桃園區水岸七街66號

TEL: 886-3-3218411 FAX: 886-3-3218422 E-mail: tec-tw@tec-robot.com.tw

潤達台中服務處：台中市烏日區太明路成豐巷98-1號

TEL: 886-4-23355629 E-mail: tec-tw@tec-robot.com.tw

上海潤漢機械設備貿易有限公司：上海市嘉定區寶安公路2999弄236號

TEL: 86-21-59106733 FAX: 86-21-69521842 E-mail: tec-sh@tec-robot.com.tw

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 ●This catalog was printed with environmentally-friendly vegetable oil ink.